

# Arduino Satellite Tracker Rotor

Christian Pack  
Team 66



THE UNIVERSITY OF  
TENNESSEE  
KNOXVILLE



# Problem Definition and Background

---

- Antenna and satellite communication relies on clear access to the Electromagnetic Waves that are transmitted and received.
- On-ground antennas require adjusting orientation towards objects orbiting within Low Earth Orbit.



# Requirements and Specifications

---

## Antenna Rotor

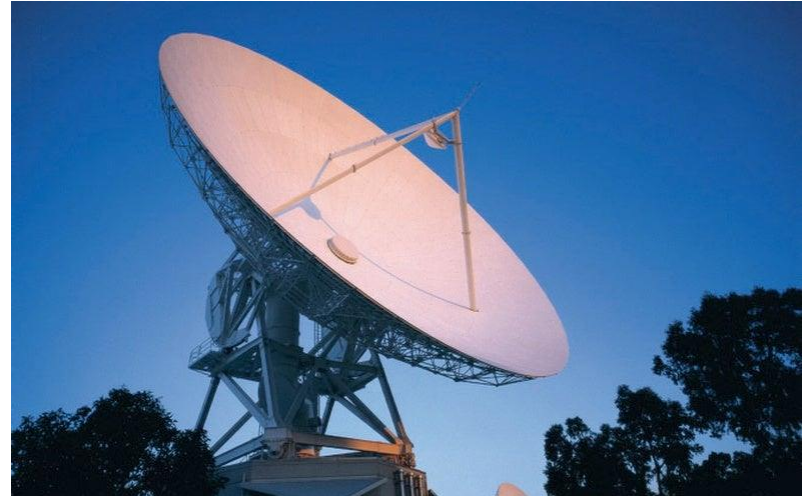
- Design an antenna rotor device that utilizes an Arduino Uno paired with Satellite Tracking software.

## Portable Use

- Use plastic box to house components to enable compact, portable usage.

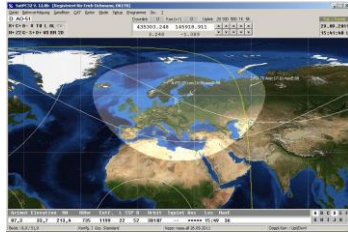
## Communicate Information

- Display important information on an LCD:
  - Azimuth and Elevation Positions
  - Desired Tracked Satellite
  - Current Time



# Technical Approach

## Communication



SatPC32



Arduino Uno Microcontroller

## Orientation Control

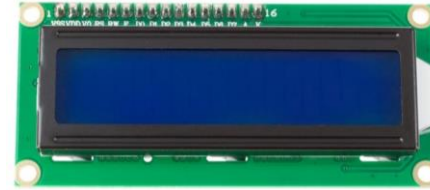


Servo Motor



Stepper Motor + ULN2003  
Motor Driver

## Display Information



Liquid Crystal Display + 10K Ohm  
Potentiometer

## Additional Pieces



Compass



Plastic  
Container



Power Supply  
Module

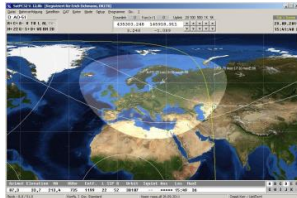
# Design Decision Identification

## 1. Satellite Tracking:

SatPC32 utilizes orbital perturbation models to track satellites.

Calculates elevation and azimuth orientation based off user's coordinates.

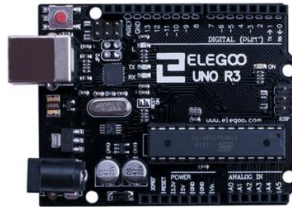
Outputs commands through serial COM port.



## 2. Data Manipulation:

Arduino sketch's general operation:

1. Interpret serial port and store Az./El. as variables.
2. Control stepper motor (Azimuth)
3. Control servo motor (Elevation)
4. Display information such as current SAT and time.



## 3. Orientation Control:

Rotor must orient along two axes: azimuth and elevation.

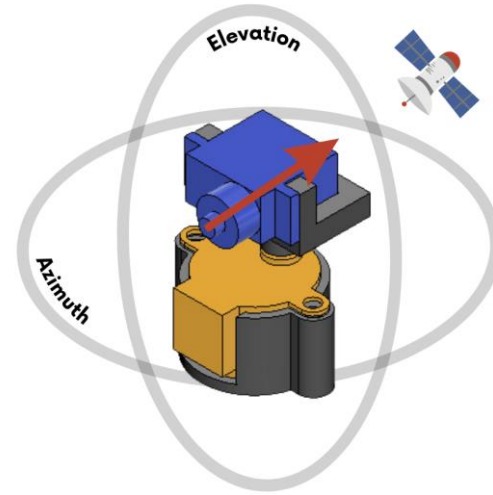
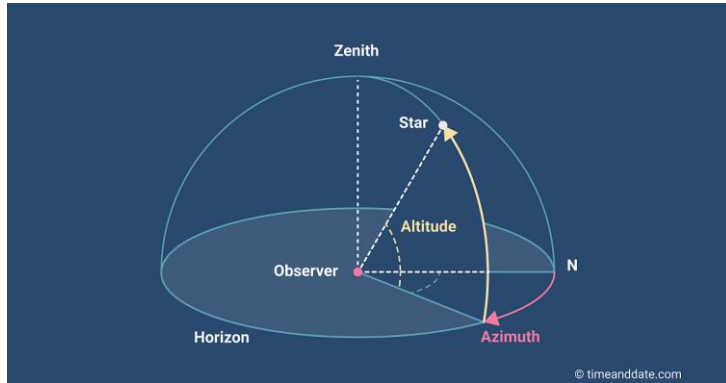
3 possible axes controls:

1. Servo + Servo
2. **Stepper + Servo**
3. Stepper + Stepper (Ideal)



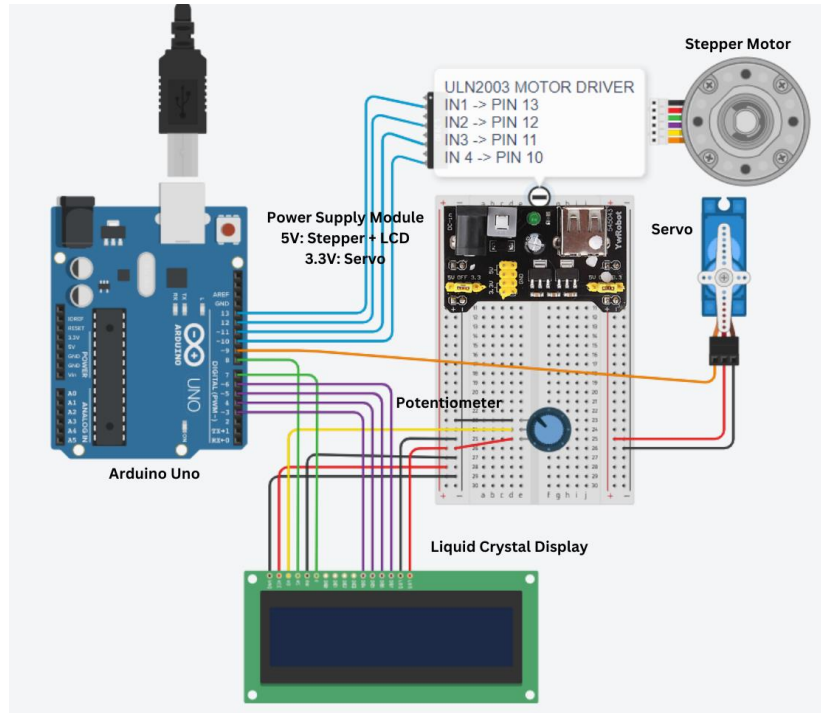
# Orientation Control

- Azimuth: Stepper Motor has 2048 steps which prevents angle error at large distances. 360 degrees is now mapped to 2048.
- Elevation: Servo motor has 0-to-180-degree control over antenna orientation.



Fusion360  
Rotor  
Mockup

# Circuit Diagram



## Unit can be powered one of two ways:

1. Elegoo 9V AC Adapter (outlet required)
2. Battery Pack with 9V Connector (for mobile use)



AC Adaptor



AA Battery Pack

# Assembled Project

---

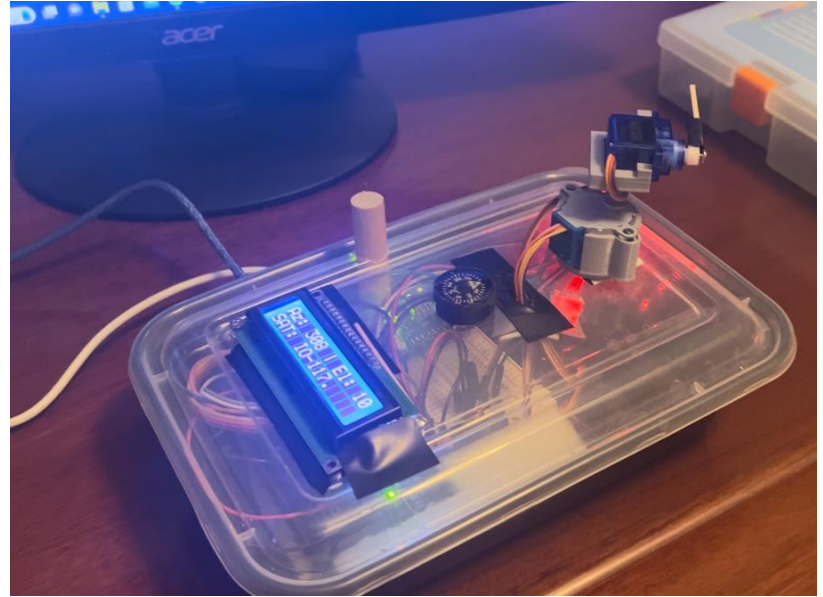


[https://www.youtube.com/watch?v=jSG6fBYsqfE&ab\\_channel=ChristianPack](https://www.youtube.com/watch?v=jSG6fBYsqfE&ab_channel=ChristianPack)

# Project Evaluation

---

- Project was a success in determining location of satellite passing by.
- Antenna rotor was tested with multiple satellites for relative accuracy.



# Future Improvements

- Modified with battery pack for mobile use.
- Improve enclosure appeal and cohesiveness.
- Model antenna that encapsulates rotor for appropriate look.
- Display current time; if N/A, display next pass time.



# Conclusion

Arduino Satellite Tracker can successfully provide corrected access to satellite's passing overhead.



THE UNIVERSITY OF  
TENNESSEE  
KNOXVILLE